

# Package: Rduino (via r-universe)

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**Title** A Microcontroller Interface

**Description** Functions for connecting to and interfacing with an 'Arduino' or similar device. Functionality includes uploading of sketches, setting and reading digital and analog pins, and rudimentary servo control. This project is not affiliated with the 'Arduino' company, <<https://www.arduino.cc/>>.

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**License** GPL-3

**Depends** serial

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**Repository** <https://pdhoff.r-universe.dev>

**RemoteUrl** <https://github.com/pdhoff/rduino>

**RemoteRef** HEAD

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BoardControlIno	<i>BoardControlIno</i>
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### Description

Board control file for the arduino and similar devices

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getApin	<i>Get analog pin</i>
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### Description

Get the value of an analog pin

### Usage

```
getApin(pin)
```

### Arguments

pin                    the number of the pin to get (integer)

### Value

the value of the pin.

### Examples

```
## Not run:
rduinoConnect()
# set position of servo to position of potentiometer
off<-getDpin(4)
while (!off)
{
  angle<-getApin(5)
  angle<- 1.68 * angle + 575
  setServo(9,angle)
  off<-getDpin(4)
}
offServo()
```

```
rduinoClose()  
## End(Not run)
```

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getDpin	<i>Get digital pin</i>
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**Description**

Get the value of a digital pin

**Usage**

```
getDpin(pin)
```

**Arguments**

pin                    the number of the pin to get (integer)

**Value**

the binary value of the pin.

**Examples**

```
## Not run:  
rduinoConnect()  
# LED remains on until button is pressed  
setDpin(5,1)  
isPressed<-getDpin(4)  
while (!isPressed){ isPressed<-getDpin(4) }  
setDpin(5,0)  
rduinoClose()  
  
## End(Not run)
```

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offServo	<i>Off servo</i>
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**Description**

deactivate a servo

**Usage**

```
offServo()
```

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offSignal	<i>Off Signal</i>
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**Description**

Turns off the square wave generated by onSignal

**Usage**

```
offSignal()
```

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onServo	<i>Set servo</i>
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**Description**

Activate a servo and set a value

**Usage**

```
onServo(pin, value)
```

**Arguments**

pin	the number of the pin connected to the servo
value	value to set for the servo

**Examples**

```
## Not run:
rduinoConnect()
# set position of servo to position of potentiometer
off<-getDpin(4)
while (!off)
{
  angle<-getApin(5)
  angle<- 1.68 * angle + 575
  setServo(9,angle)
  off<-getDpin(4)
}
offServo()

rduinoClose()

## End(Not run)
```

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onSignal	<i>On Signal Generate a square wave, from 1Hz to 31.25kHz, with resolution of 16us</i>
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**Description**

On Signal Generate a square wave, from 1Hz to 31.25kHz, with resolution of 16us

**Usage**

```
onSignal(freq, dutyCycle1, dutyCycle2)
```

**Arguments**

freq	the frequency of the wave, in Hz
dutyCycle1	the percentage of time that pin 9 should spend at HIGH
dutyCycle2	the percentage of time that pin 10 should spend at HIGH

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rduinoClose	<i>Rduino disconnect</i>
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**Description**

Disconnect a previously connected Arduino or similar device

**Usage**

```
rduinoClose()
```

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rduinoConnect	<i>Rduino connect</i>
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**Description**

Make a serial connection to an Arduino or similar device

**Usage**

```
rduinoConnect(baud = 38400, mode = "n,8,1", upload = FALSE,  
arduino = NULL, sdPin = 8)
```

**Arguments**

baud	baud rate
mode	communication mode
upload	if TRUE, upload the ino file to the device
arduino	command used to run arduino as a shell command including the path This function does two things - uploads a .ino file to an Arduino, and acts as a wrapper for the serialConnection function of the serial package. The options for the communication mode are available via the helpfile for the serialConnection command.

**Examples**

```
## Not run:
rduinoConnect()
rduinoClose()

## End(Not run)
```

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rduinoSample

*Rduino Sample*


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**Description**

Samples in as quickly as possible from given pin for specified duration

**Usage**

```
rduinoSample(readPin, time)
```

**Arguments**

readPin	the analog pin to read in from
time	the length of time (ms) that the Arduino should read data for

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setApin	<i>Set analog pin</i>
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**Description**

Set a analog pin to on or off

**Usage**

```
setApin(pin, value)
```

**Arguments**

pin	the number of the pin to set (integer)
value	the value to which to set the pin (real)

**Examples**

```
## Not run:  
rduinoConnect()  
# gradually increase intensity of LED  
for (i in seq(1,256,by=5))  
{  
  setApin(11,i)  
  Sys.sleep(0.05)  
}  
rduinoClose()  
  
## End(Not run)
```

---

setDpin	<i>Set digital pin</i>
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---

**Description**

Set a digital pin to on or off

**Usage**

```
setDpin(pin, value)
```

**Arguments**

pin	the number of the pin to set (integer)
value	the value to which to set the pin (binary)

**Examples**

```
## Not run:
rduinoConnect()
# flash LED rapidly
for (i in 0:9)
{
  setDpin(8,1)
  Sys.sleep(0.05)
  setDpin(8,0)
  Sys.sleep(0.05)
}
rduinoClose()

## End(Not run)
```



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